ATESTEO

Excellence in drivetrain testing

Data sheet

FxiS / FxeS

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Torque measuring system					
Technology	-	Rotating			
Rated torque (Md_n) #1	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Rated torque short measurement range (optional, minimum) (Md_{ns}) #2	Nm	N/A 70 140	170 340	N/A 70 140	170 340
Accuracy class extended (for Md_n)	%	N/A			
Outputs	-	Frequency (RS422), Voltage, Current, CAN bus, Alert			
Test signal	-	see test report			
Mechanical dimensions #3					
Outer diameter of rotor #4	mm	95.50			
Lengths (Rotor, without centering)	mm	54			
Pitch circle diameter #5	mm	75.0			
Speeds and speed measuring systems					
Speed detection (integrated)	-	without			
Speed detection (optional)	-	optical			
Maximum Speed without speed detection system	rpm	20,000			
Optional increased speed	rpm	30,000			
Maximum speed with magnetic speed encoder	rpm	N/A			
Maximum speed with optical speed encoder #6	rpm	up to 20,000			
Maximum speed with inductive speed encoder	rpm	N/A			
Torque accuracy class per output type (related to Md_n)					
Frequency output	%	≤±0.05			
CAN output	%	≤±0.05			
Voltage output	%	≤±0.10			
Current output	%	≤±0.10			
Frequency output (option higher accuracy)	%	N/A			
CAN (option higher accuracy)	%	N/A			

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Linearity deviation including hysteresis related to Md_n #7					
Frequency, 0%...30%	%	≤±0.010			
Frequency, 30%...60%	%	≤±0.020			
Frequency, 60%...100%	%	≤±0.030			
CAN, 0%...30%	%	≤±0.010			
CAN, 30%...60%	%	≤±0.020			
CAN, 60%...100%	%	≤±0.030			
Voltage output	%	≤±0.05			
Current output	%	≤±0.05			
Rel. standard deviation of the reproducibility according to DIN 1319, by reference to variation of the output signal (rel. to Md_n)					
Frequency output	%	≤±0.03			
CAN output	%	≤±0.03			
Voltage output	%	≤±0.05			
Current output	%	≤±0.05			
Temperature influence per 10K in the nominal temperature range on the output signal related to the actual value of signal span (rel. to Md_n)					
Frequency output	%	≤±0.05			
CAN output	%	≤±0.05			
Voltage output	%	≤±0.10			
Current output	%	≤±0.10			
Temperature influence per 10K in the nominal temperature range on the zero signal (rel. to Md_n)					
Frequency output	%	≤±0.05			
CAN output	%	≤±0.05			
Voltage output	%	≤±0.10			
Current output	%	≤±0.10			
Long-term drift over 48h at reference temperature					
Voltage output	mV	<1.0			
Current output	µA	<0.80			

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Nominal sensitivity (range between zero torque and rated torque)					
Frequency output	kHz	20			
Voltage output	V	5.0 / 10.0 / 2.5 / 5.0			
Current output	mA	8 / 10			
Output signal at zero torque					
Frequency output	kHz	60			
Voltage output	V	0.0 / 0.0 / 2.5 / 5.0			
Current output	mA	12 / 10			
Nominal output signal					
Frequency output at positive nominal value	kHz	80			
Frequency output at negative nominal value	kHz	40			
Voltage output at positive nominal value	V	5 / 10 / 5 / 10			
Voltage output at negative nominal value	V	-5 / -10 / 0 / 0			
Current output at positive nominal value	mA	20 / 20			
Current output at negative nominal value	mA	4 / 0			
Max. modulation range					
Frequency output	kHz	30...90			
Voltage output	V	-10.5...10.5			
Current output	mA	0...24			
Group delay time (main TCU)					
Frequency output	µs	10			
Voltage output	µs	3,000			
CAN bus	µs	1,000			

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000

Speed measuring system	**Inductive (track at rotor)**	
Pulse per rev (PPR)	ppr.	N/A
Maximum speeds (related to PPR)	rpm	N/A
Max. output frequency (RS422)	kHz	N/A
Minimum speed for sufficient pulse stability	rpm	N/A
Speed measuring system	**Magneto resistive (2 tracks approx. 90 degree phase shifted)**	
Pulses per rev (PPR)	ppr.	N/A
Maximum speeds (related to PPR)	rpm	N/A
Max. output frequency (RS422)	kHz	N/A
Minimum speed for sufficient pulse stability	rpm	N/A
Nominal clearance (sensor - pole ring)	mm	N/A
Working airgap (sensor - pole ring)	mm	N/A
Nominal axial displacement (rotor - stator) #8	mm	N/A
Tolerance to nominal axial displacement (rotor - stator)	mm	N/A
Speed measuring system	**Optical**	
Pulses per rev (PPR)	ppr.	240 / 360 / 400
Maximum speeds (related to PPR)	rpm	20,000 / 16,000 / 15,000
Max. output frequency (RS422)	kHz	80 / 96 / 100
Minimum speed for sufficient pulse stability	rpm	>1.3 / >0.8 / >0.8
Nominal radial displacement (rotor - stator)	mm	1.5
Tolerated radial displacement (rotor - stator) #8	mm	1.4...1.6
Nominal axial displacement (rotor - stator) #8	mm	4.0
Tolerance to nominal axial displacement (rotor - stator)	mm	+0.5/-0.3

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000

Angular measuring system		
Pulses per rev	ppr.	N/A
Resolution	°	N/A
Output signals	-	N/A
Measurement ranges	°	N/A

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Temperature ranges					
Nominal temperature range *(Rotor)*	°C	0...80			
Operating temperature range *(Rotor)* *#9*	°C	-20...85			
Storage temperature range *(Rotor)*	°C	-30...85			
Nominal temperature range *(Stator)*	°C	0...70	0...70	0...80	0...80
Operating temperature range *(Stator)* *#10*	°C	-20...70	-20...70	-20...85	-20...85
Storage temperature range *(Stator)*	°C	-30...85			
Nominal temperature range *(TCU)*	°C	N/A	N/A	0...70	0...70
Operating temperature range *(TCU)*	°C	N/A	N/A	-20...70	-20...70
Storage temperature range *(TCU)*	°C	N/A	N/A	-30...85	-30...85
Mechanical shock (EN 60068-2-27)					
Quantity	-	1,000			
Duration	ms	3			
Acceleration	m/s²	650			
Vibration load (EN 60068-2-6)					
Frequency	Hz	10...2,000			
Duration	min.	150			
Acceleration	m/s²	200			
Load limits #11					
Limit torque, related to Md_n	%	500 500 325	325 275	500 500 325	325 275
Breaking torque approx., related to Md_n	%	1,000 1,000 650	650 550	1,000 1,000 650	650 550
Axial limit force	kN	10.00 20.00 23.90	27.00 52.90	10.00 20.00 23.90	27.00 52.90
Lateral limit force	N	2,060.00 4,260.00 5,530.00	6,590.00 12,300.00	2,060.00 4,260.00 5,530.00	6,590.00 12,300.00
Bending limit torque	Nm	64.00 130.00 162.50	190.50 389.50	64.00 130.00 162.50	190.50 389.50

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Mechanical values					
Torsional stiffness	kNm/rad	181 380 493	586 975	181 380 493	586 975
Angle of twist at Md_n	°	0.032 0.030 0.046	0.049 0.059	0.032 0.030 0.046	0.049 0.059
Axial stiffness	kN/mm	400 803 959	1,082 2,115	400 803 959	1,082 2,115
Radial stiffness	kN/mm	128 266 345	412 769	128 266 345	412 769
Bending stiffness	kNm/°	1.80 3.70 4.60	5.40 11.10	1.80 3.70 4.60	5.40 11.10
Deflection at axial limit force	mm	<0.03			
Additional radial deviation at lateral limit force	mm	<0.02			
Parallel deviation at bending limit torque	mm	<0.06			
Inherent frequency	Hz	3,100 3,300 3,700	4,100 5,700	3,100 3,300 3,700	4,100 5,700
Balance quality-level (DIN ISO 1949)	-	G2.5			
Inertia of rotor	kgm²	0.0007 0.0013 0.0013	0.0013 0.0011	0.0007 0.0013 0.0013	0.0013 0.0011
Max. limits for relative shaft vibration (peak to peak) #12	µm	$S_{(p-p)} = \frac{9000}{\sqrt{n}}$			

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Weight approx.					
Rotor #13	kg	0.7 1.1 1.1	1.1 1.0	0.7 1.1 1.1	1.1 1.0
Stator (without speed encoder) #13	kg	2.10	2.10	1.10	1.10
Mounting distances (without optional speed detection system)					
Nominal radial displacement (rotor - stator)	mm	2.1			
Tolerance to nominal radial displacement (rotor - stator)	mm	≤±0.1			
Nominal axial displacement (rotor - stator) #8	mm	4			
Tolerance to nominal axial displacement (rotor - stator)	mm	≤±0.5			
Flatness and concentricity tolerances rotor					
Circular run-out-axial tolerance #14	mm	0.01			
Circular run-out-radial tolerance #14	mm	0.01			
Power supply					
Nominal supply	V	(DC) 24			
Supply range #15	V	(DC) 23...25			
Max. current consumption in measuring mode	A	<0.70			
Max. current consumption in start-up mode	A	<2			
Nominal power consumption	W	<17			
Load resistance					
Frequency output	-	RS422			
Voltage output	kOhm	≥5			
Dynamic					
Frequency output	kHz	≤7			
Voltage output	kHz	≤1			
Current output	kHz	≤1			
CAN output conversation rate	1/s	≤1,000			

Technical data

Type	-	F0iS-SV	F0iS-SV	F0eS-SV	F0eS-SV
Accuracy class	%	≤±0.05			
Rated torque (Md_n)	Nm	100 200 400	500 1,000	100 200 400	500 1,000
Miscellaneous					
Protection class *(Rotor)*	-	IP54			
Protection class *(Stator)*	-	IP54			
Protection class (rotor, extended)	-	On request			
Protection class (stator, extended)	-	On request			
Pitch circle screw information	-	4 * M10 (8.8) 4 * M10 (10.9) 4 * M10 (10.9)	4 * M10 (10.9) 8 * M10 (12.9)	4 * M10 (8.8) 4 * M10 (10.9) 4 * M10 (10.9)	4 * M10 (10.9) 8 * M10 (12.9)
CAN bus type	-	2B			
Configuration interface	-	RS232			
Central hole	mm	N/A			
Material	-	Titanium Steel Steel	Steel	Titanium Steel Steel	Steel
Measuring range (related to Md_n)	%	120			
Compatible evaluation units (TCU)	-	Integrated	Integrated	TCU2	TCU2
Stator type	-	iS	iS	eS	eS
Sales information					
Article number	-	10004634 10003315 10003315	10003315	10004635 10004186 10004186	10004186
U.S. FCC certificate	-	Not required			

Remarks and information

Link no.	Topic	Remark
#1	Nominal torque	Based on customer requests, the measurement systems can optionally be optimized for not listed nominal torque values (intermediate ranges possible).
#2	Second torque range	The written second nominal torque value (Md_{ns}) is the smallest possible. Greater second torque ranges can be chosen on demand. Mechanical values and load limits vary between single and dual range torque meters. A data sheet for dual range torque meters with specific values can be requested.
#3	Dimensions	Mechanical dimensions are without engagement. Use the drawings and step files as master for your constructions.
#4	Details in the drawings	Value can vary by optional components. Please find details to this attribute in the integrated drawings.
#5	Pitch circle diameter	The pitch circle diameter is identically at input and output side for most systems. More information is given in the drawings of a product.
#6	Speed detection max speed	The maximum allowed speed of speed detection systems is depending on the number of pulses per rotation (PPR). High PPRs can reduce the maximum allowed speed. Details are shown within this data sheet in the description of the speed detection system.
#7	Linearity	Values of Linearity deviation incl. Hysteresis can only be reached if positive and negative sensitivity values are used.
#8	Reference planes	Please check the drawings for information about the reference planes of this attribute.
#9	Temperature range (rotor)	No condensation allowed.
#10	Temperature range (stator)	No condensation allowed. Temperature related to housing ground point.

Remarks and information

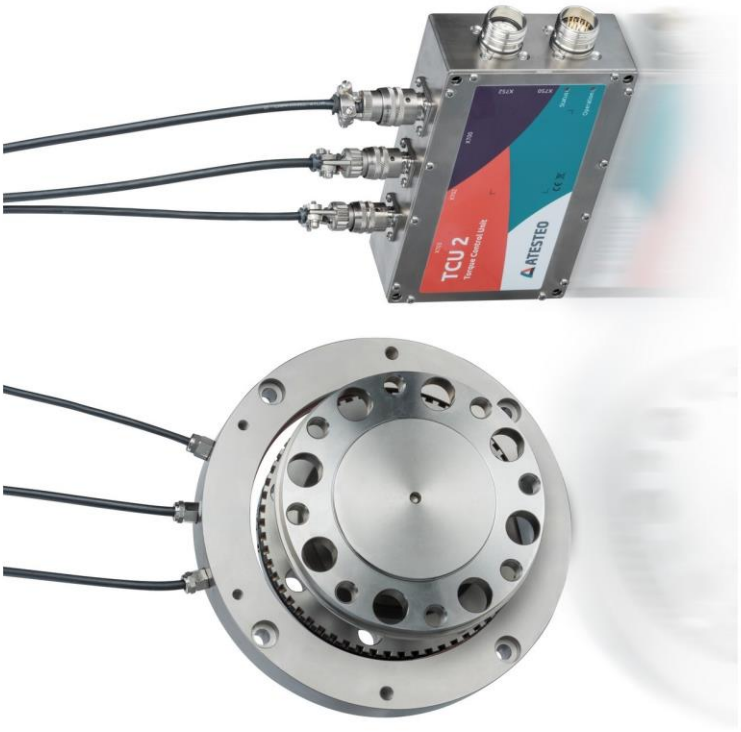
Link no.	Topic	Remark
#11	Load limits	The given values are only valid if no other load occurs at the same time. If the loads in sum are 100%, the max. error will be 0.3% of the nominal torque. Limit and break torque are lower if other loads are applied (such as lateral forces).
#12	Vibration limits	Vibration limits are not an influence to the machine. They reflect the allowed effect onto the rotor (ISO 7919-3). Parameter "n" is given in "r/min.".
#13	Weights	Weights are related to components without options like speed detection system. Please contact us for exact weight information of options.
#14	Flatness and concentricity tolerances	The parameters of "Flatness and concentricity tolerances rotor" are manufacturing tolerances.
#15	Supply voltage	The supply voltage range must be given at measurement system side. Long wires can reduce the voltage level from power supply to measurement system.

Drawing

iS

Rotor & stator with integrated evaluation unit (TCU)
Rotor & Stator mit integrierter Auswerteeinheit (TCU)

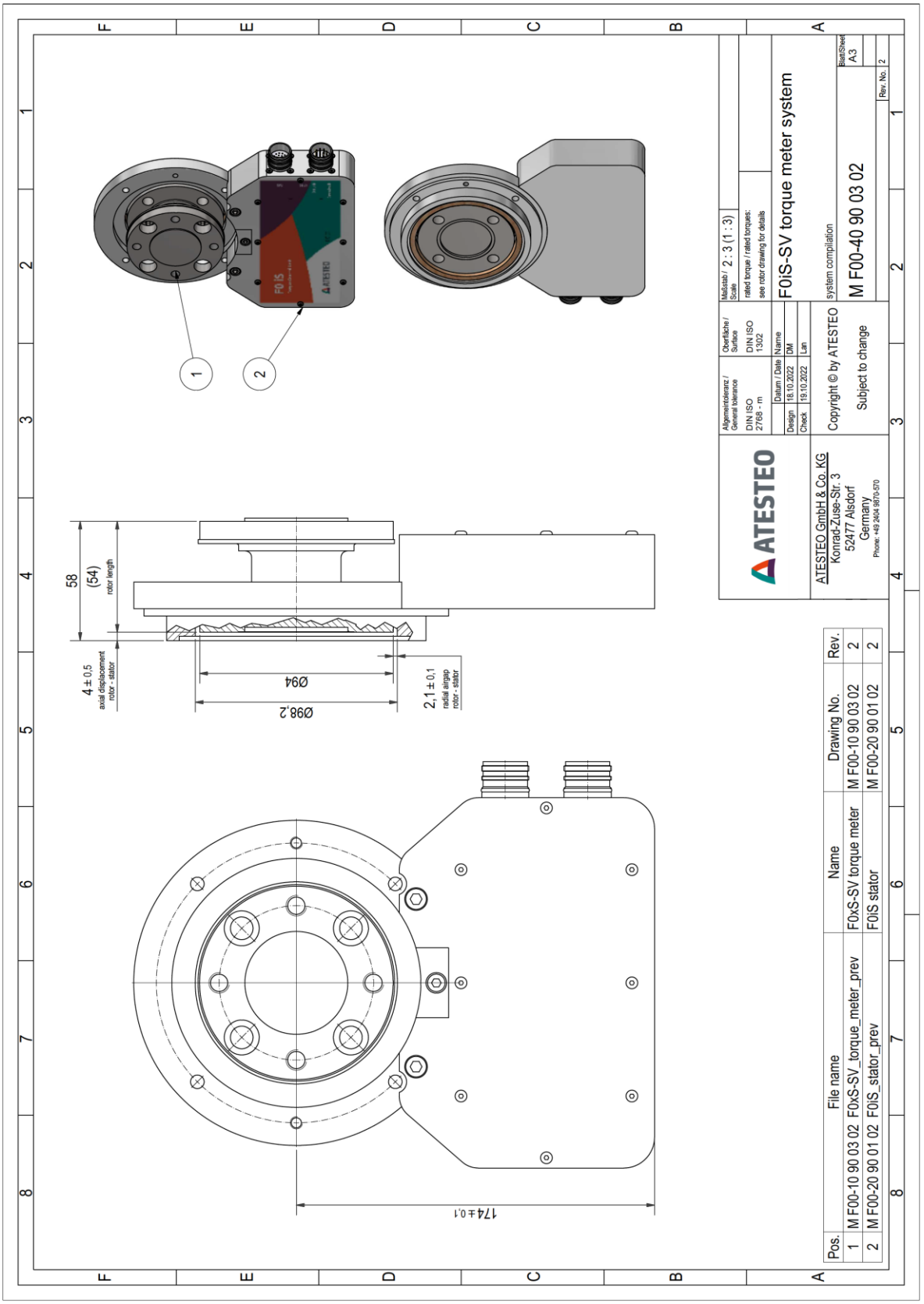
eS



Rotor, ring stator & external evaluation unit (TCU)
Rotor, Ringstator & abgesetzte Auswerteeinheit (TCU)

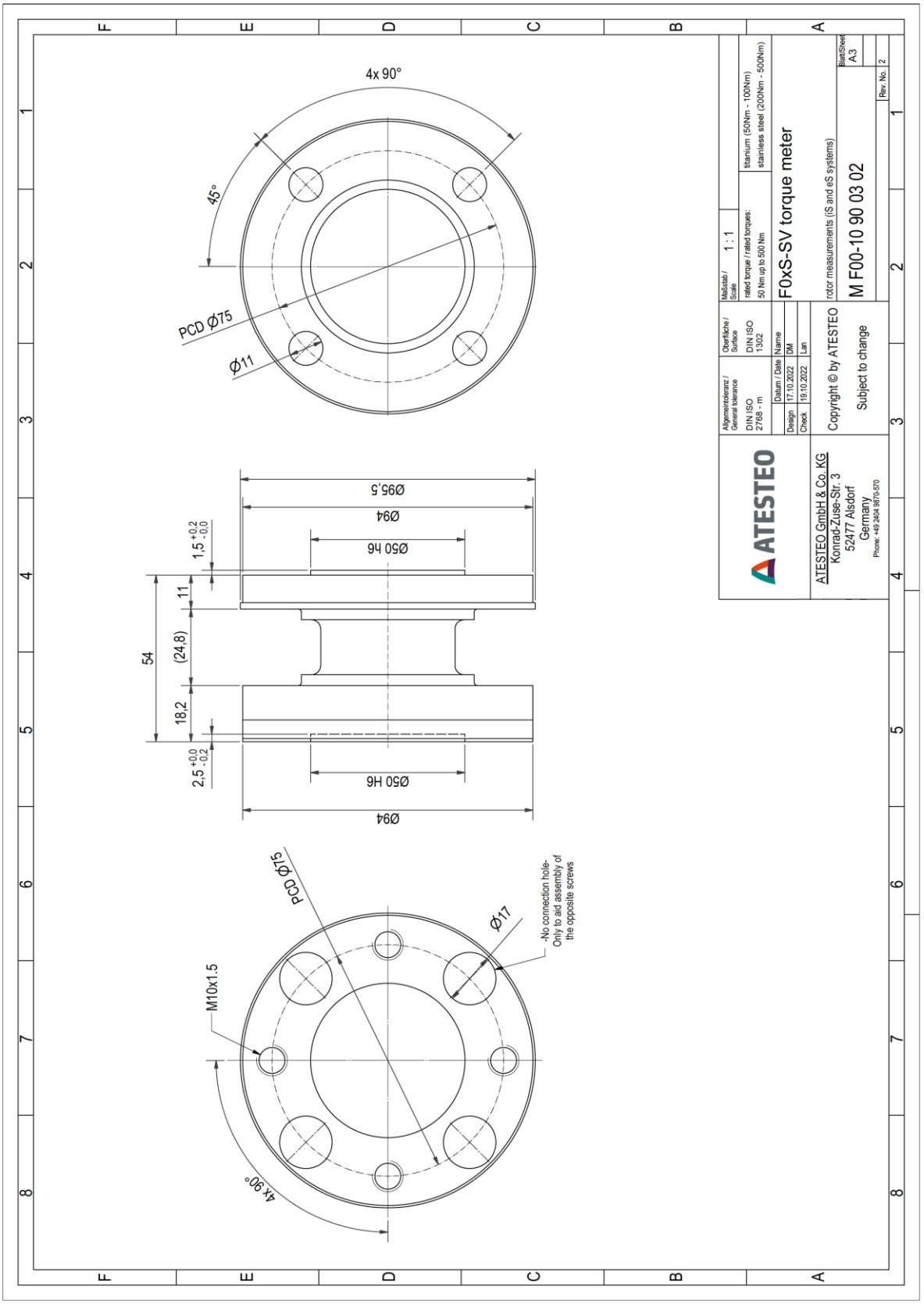
F0iS-SV (<=500 Nm) System

Drawing



F0iS-SV (<=500 Nm)
Rotor

Drawing



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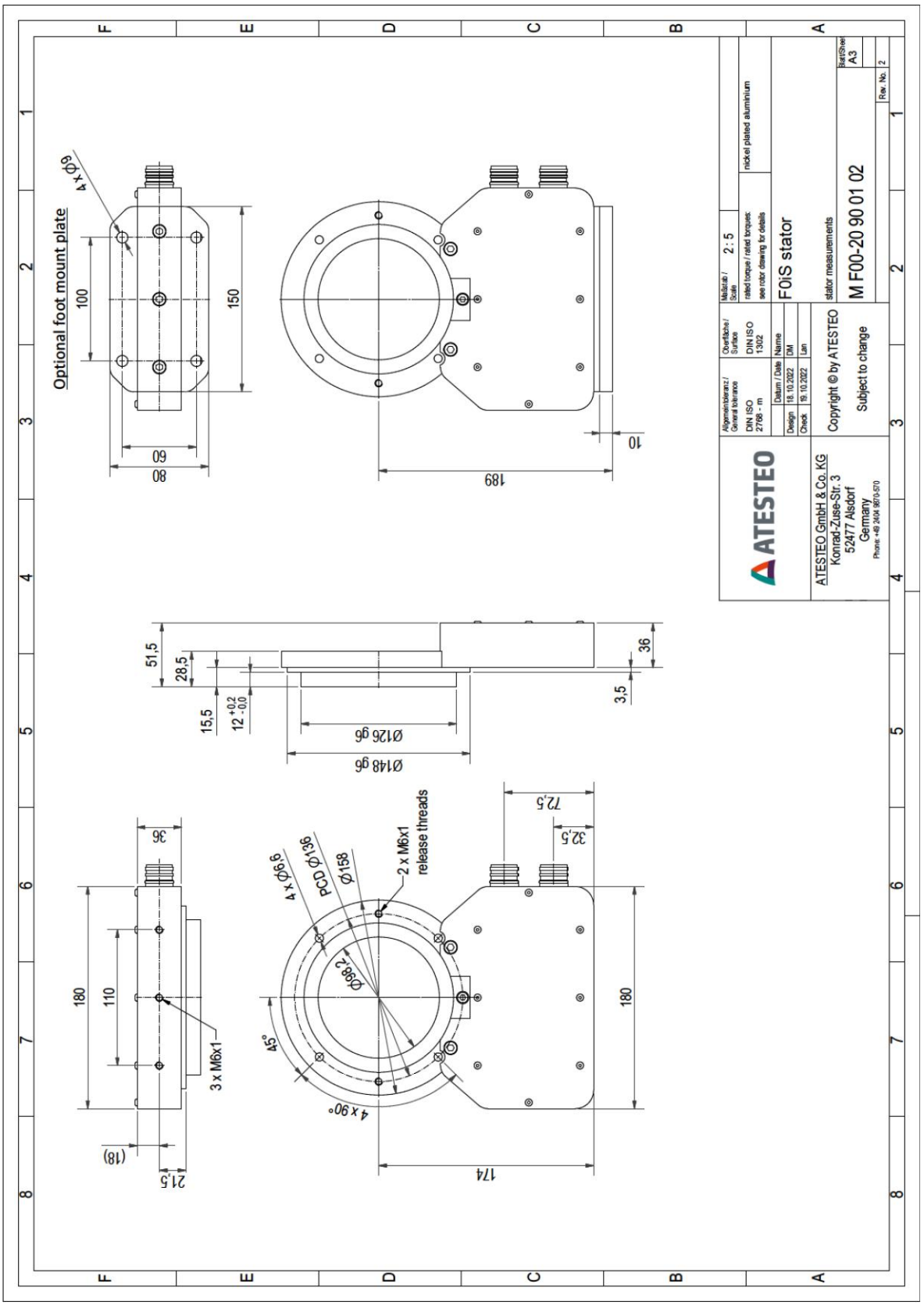
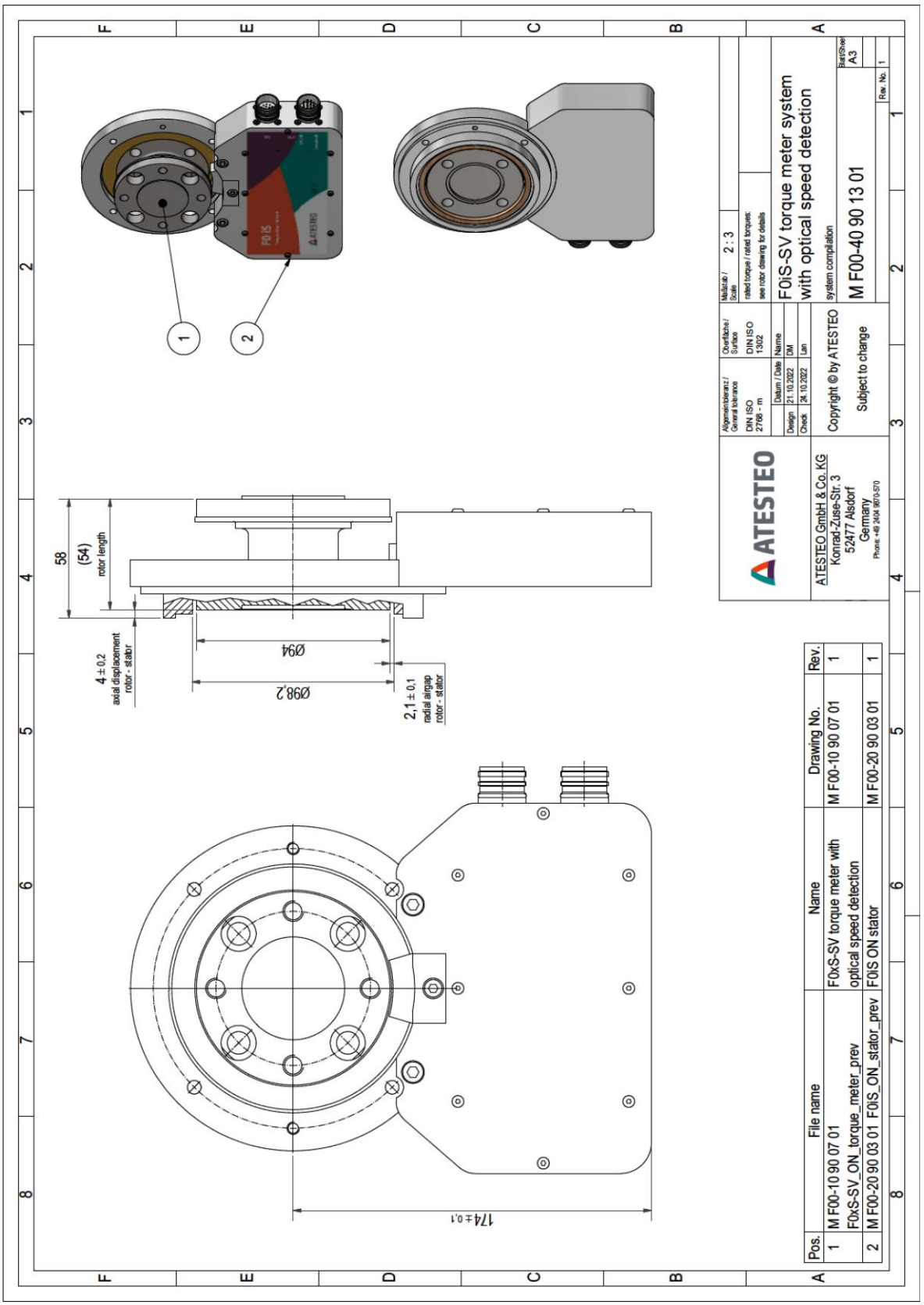


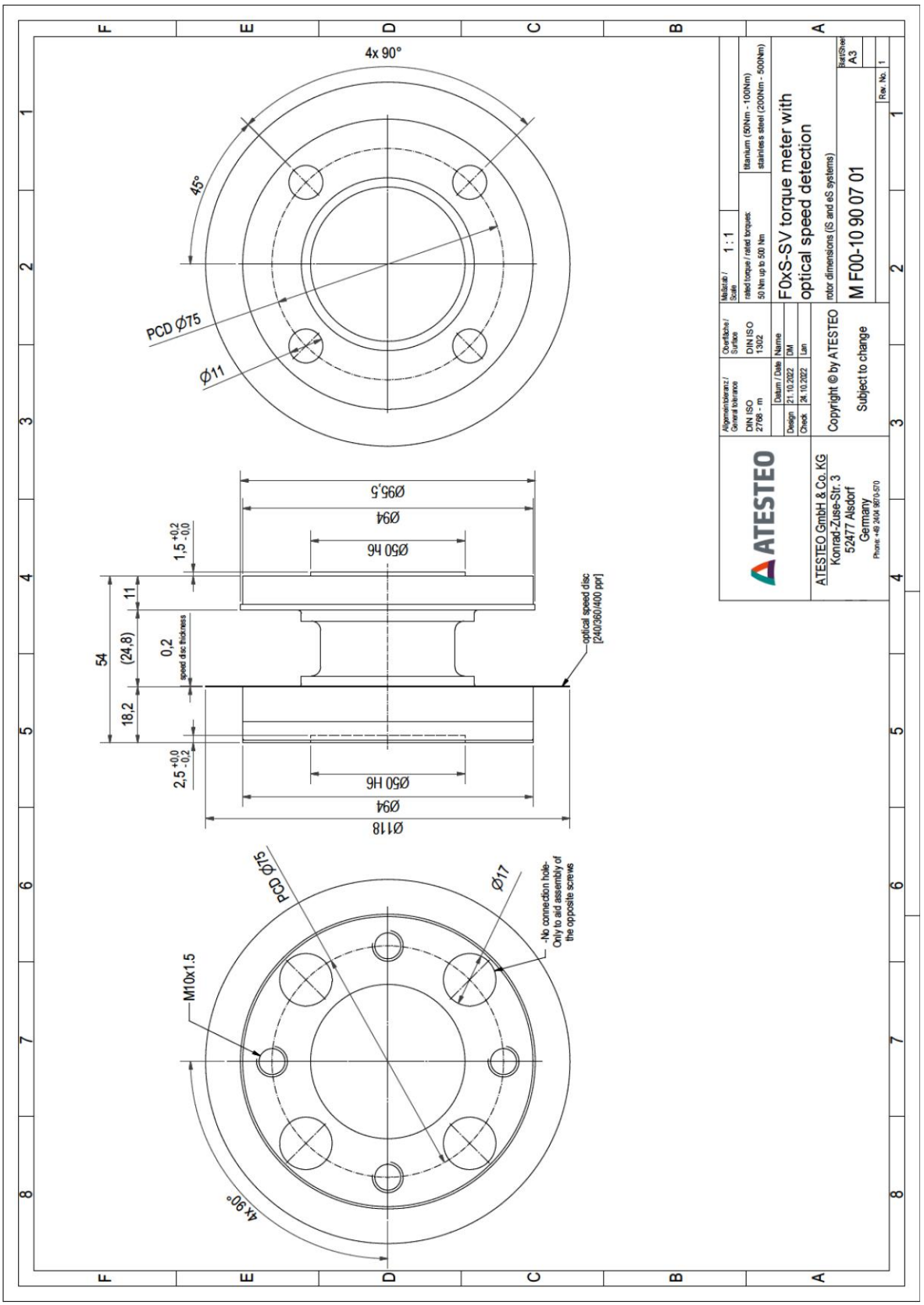
F0iS-SV SPD_OPT (<=500 Nm) System

Drawing

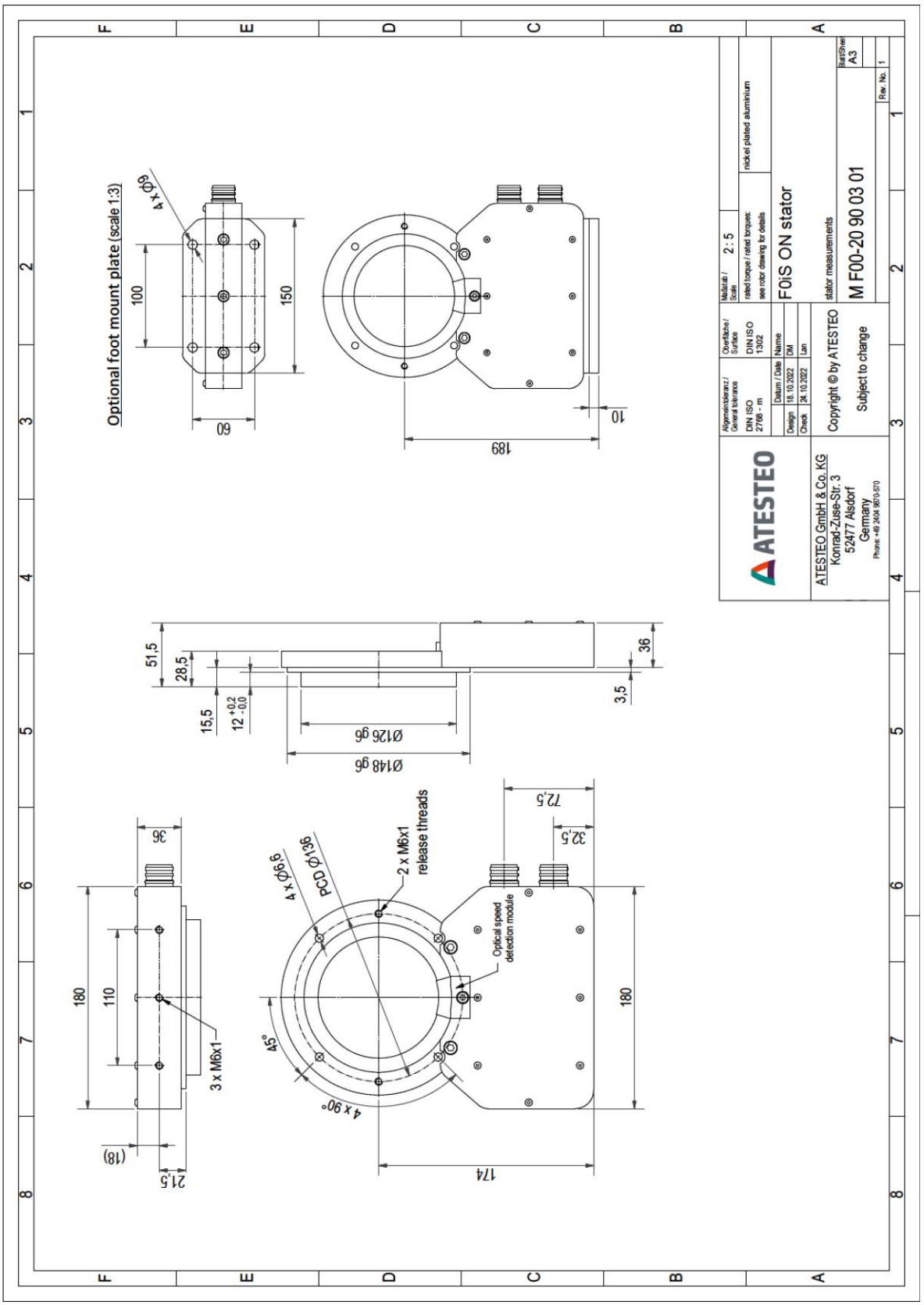


F0iS-SV SPD_OPT (<=500 Nm) Rotor

Drawing

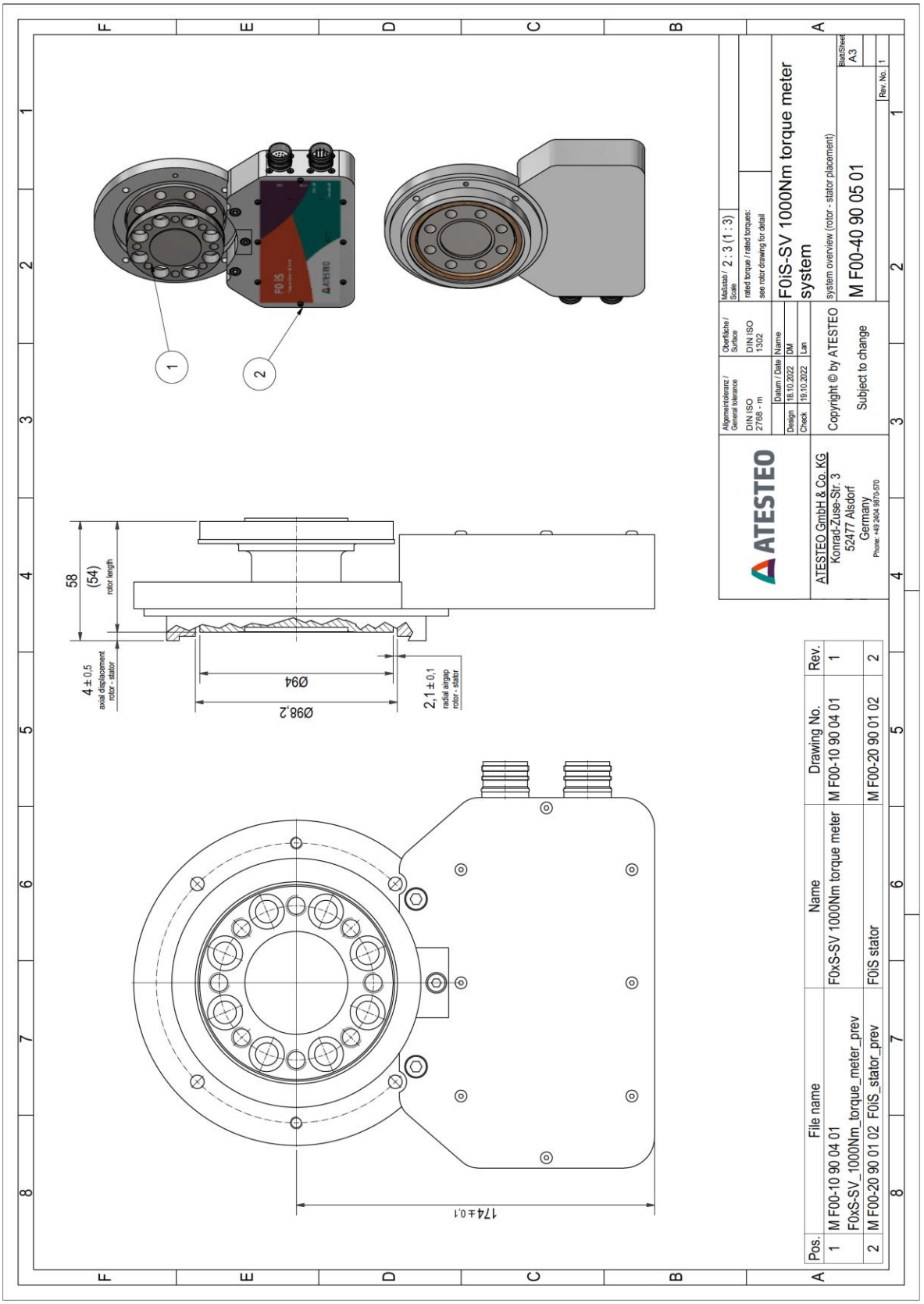


Drawing

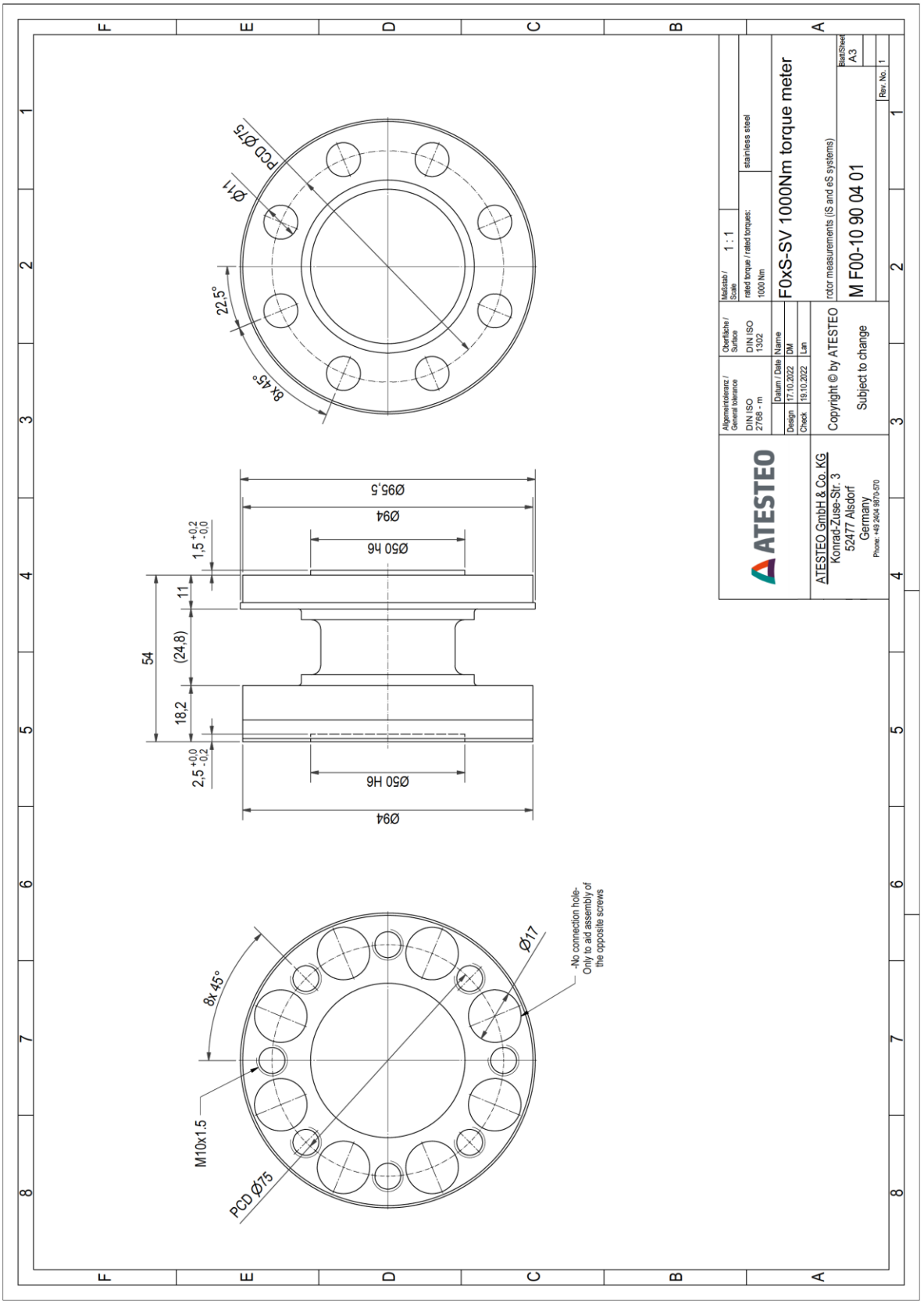


F0iS-SV (1000 Nm) System

Drawing

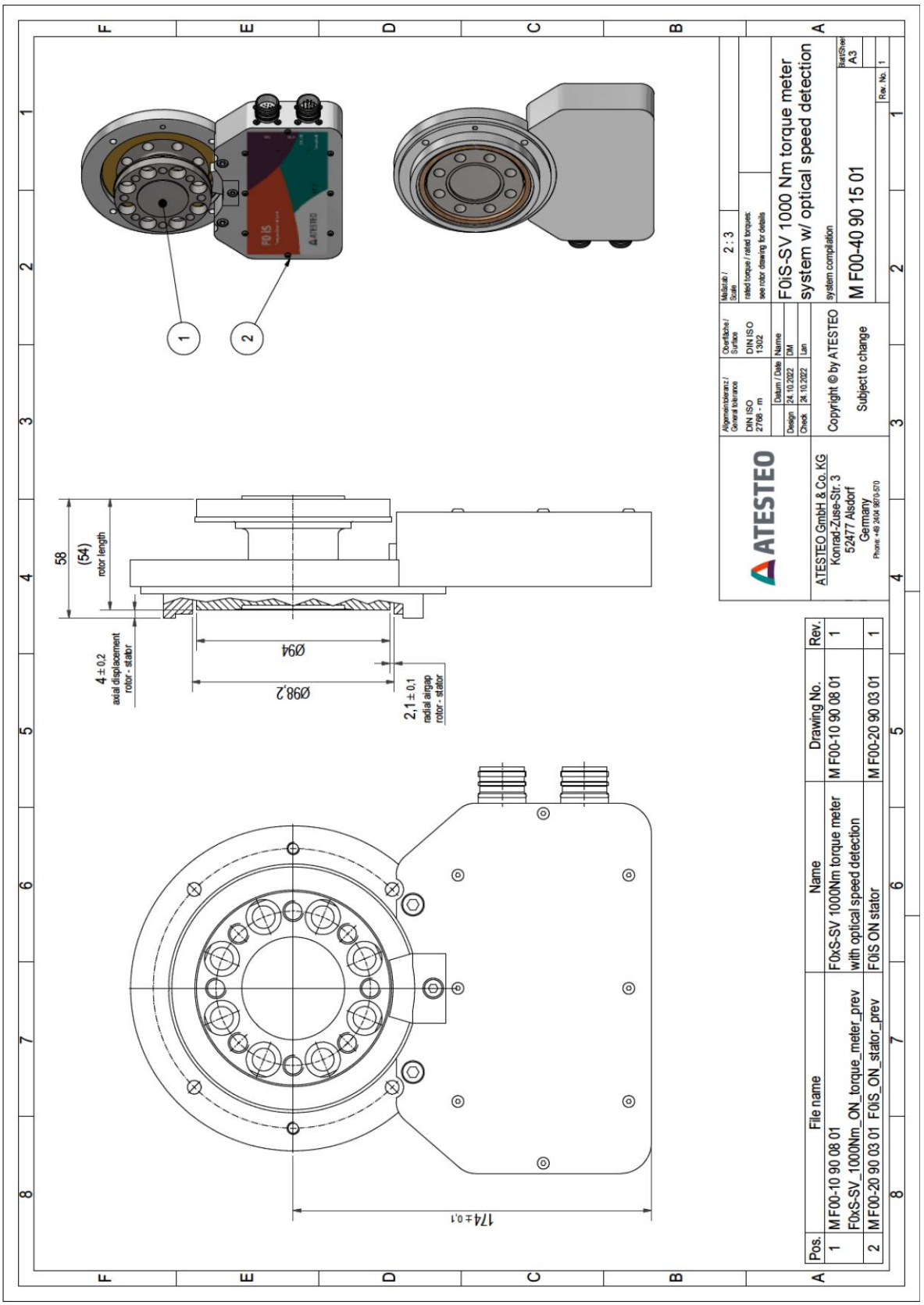


Drawing



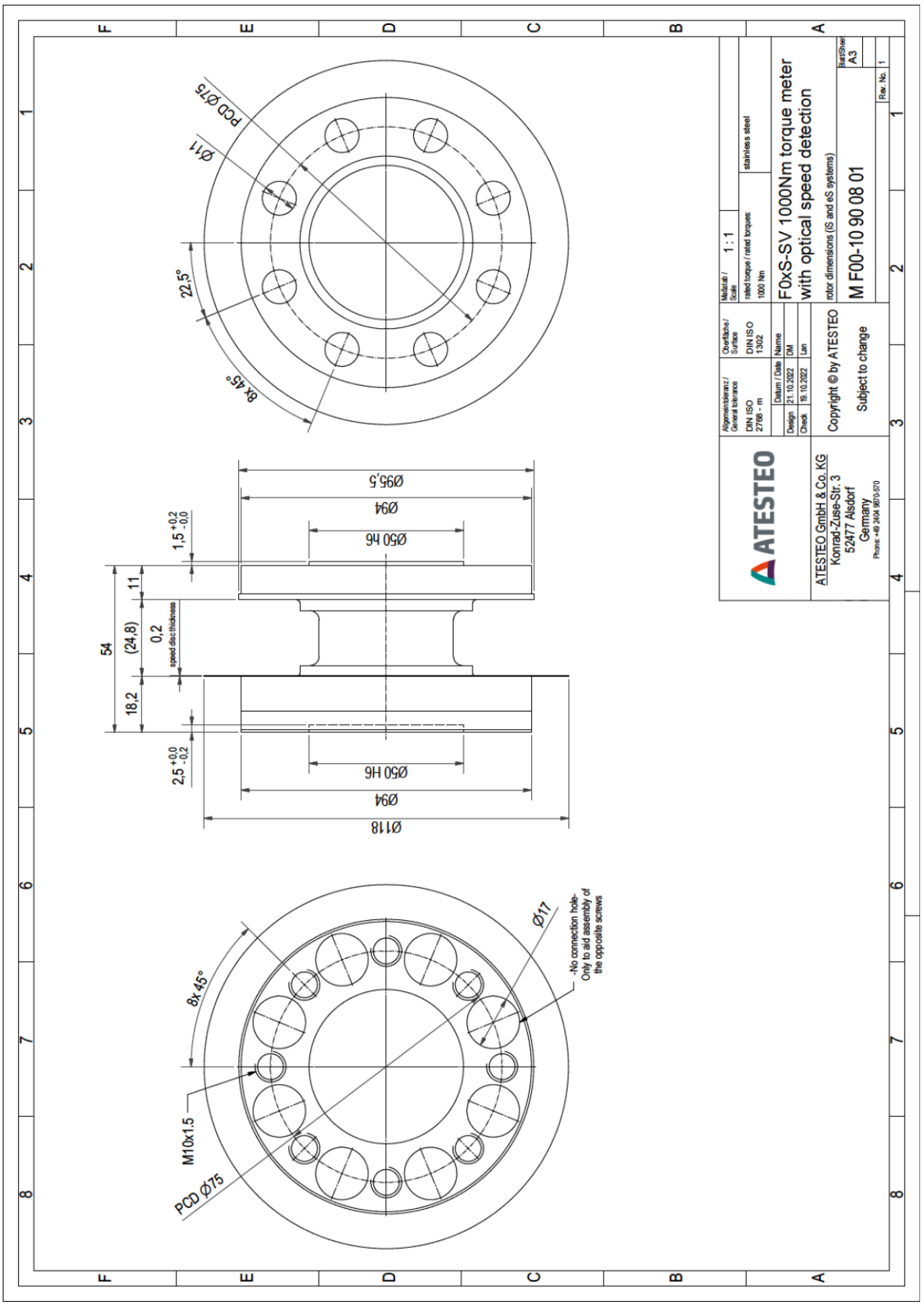
F0iS-SV SPD_OPT (1000 Nm) System

Drawing



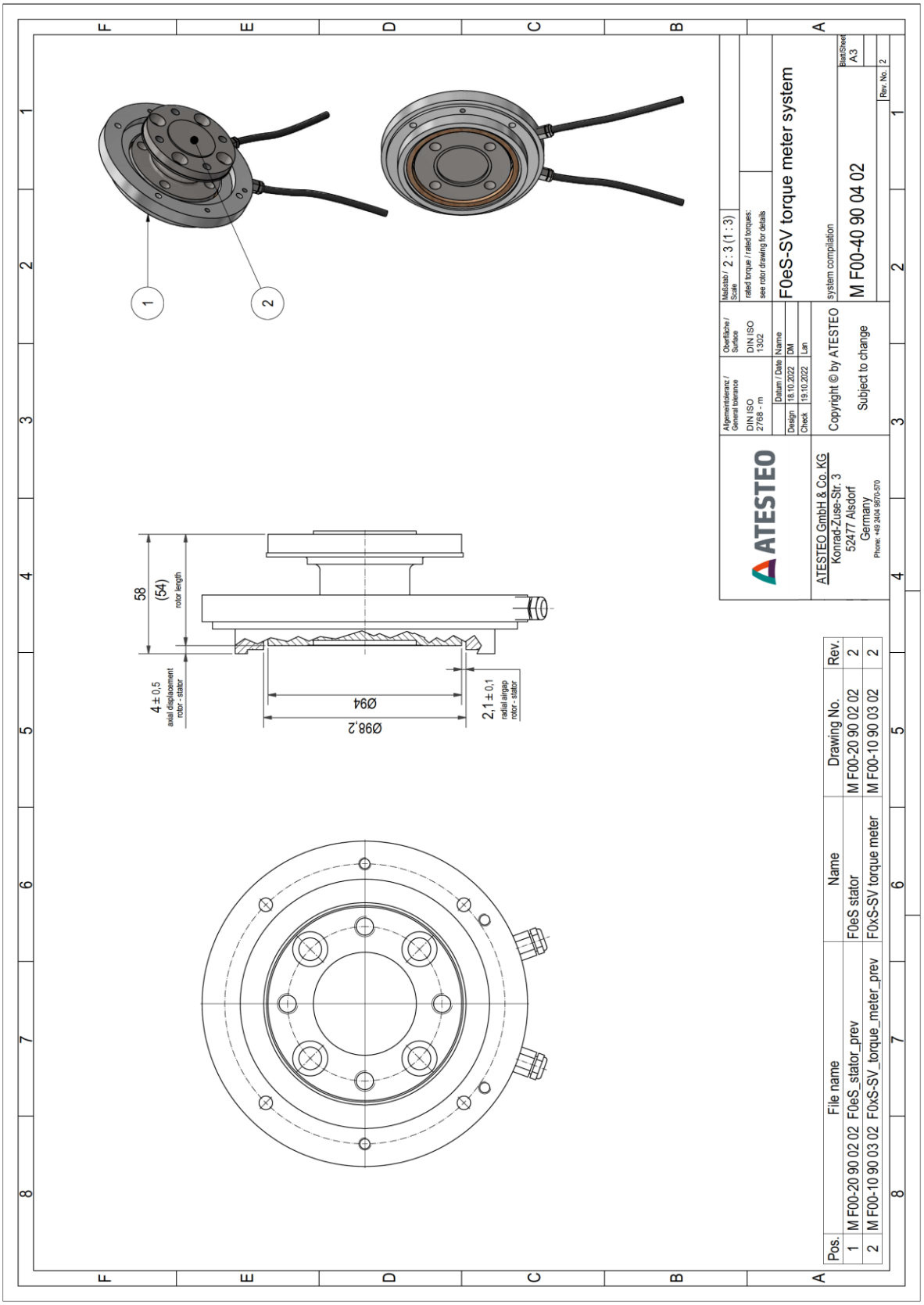
F0iS-SV SPD_OPT (1000 Nm) Rotor

Drawing



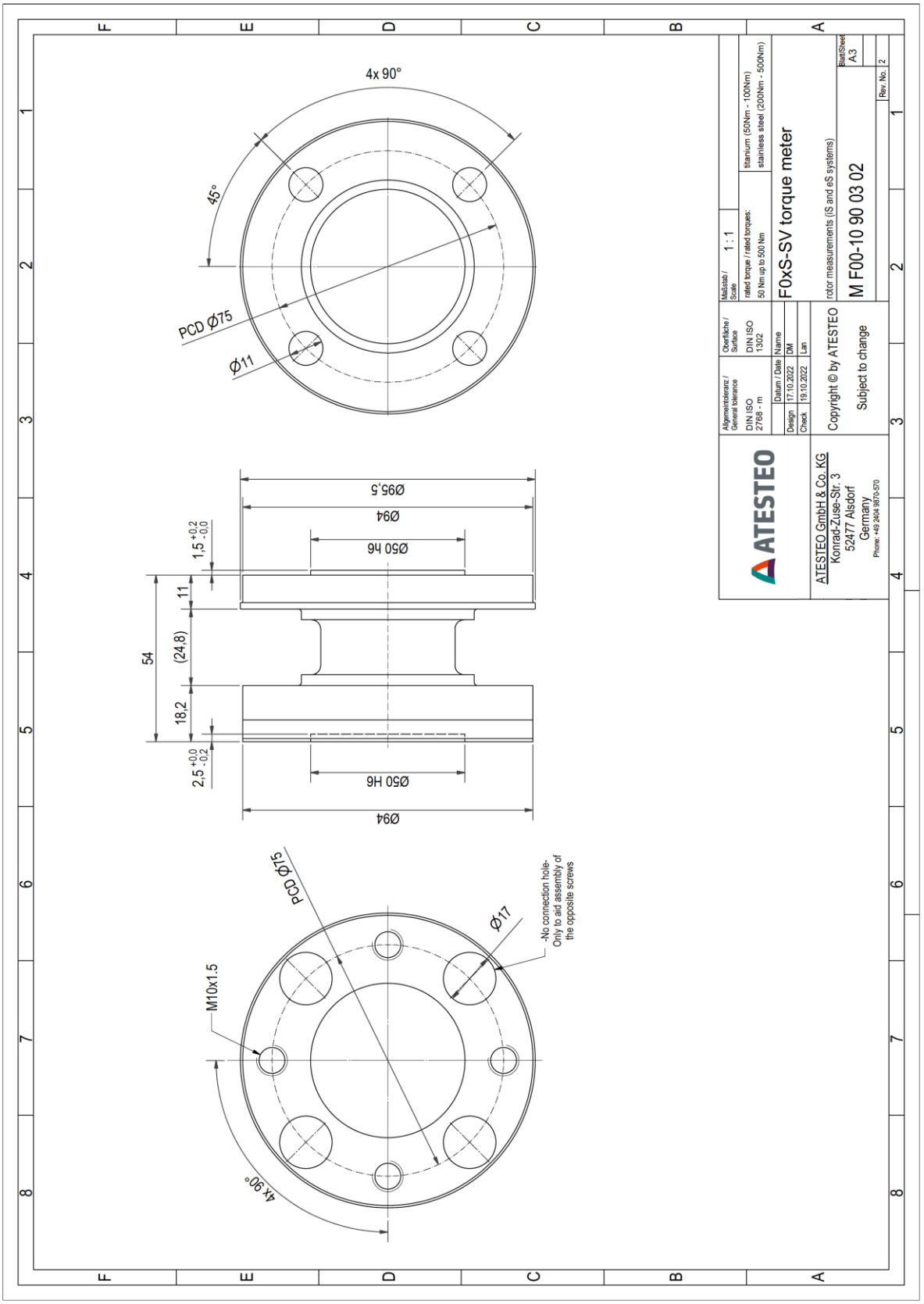
F0eS-SV (<=500 Nm) System

Drawing

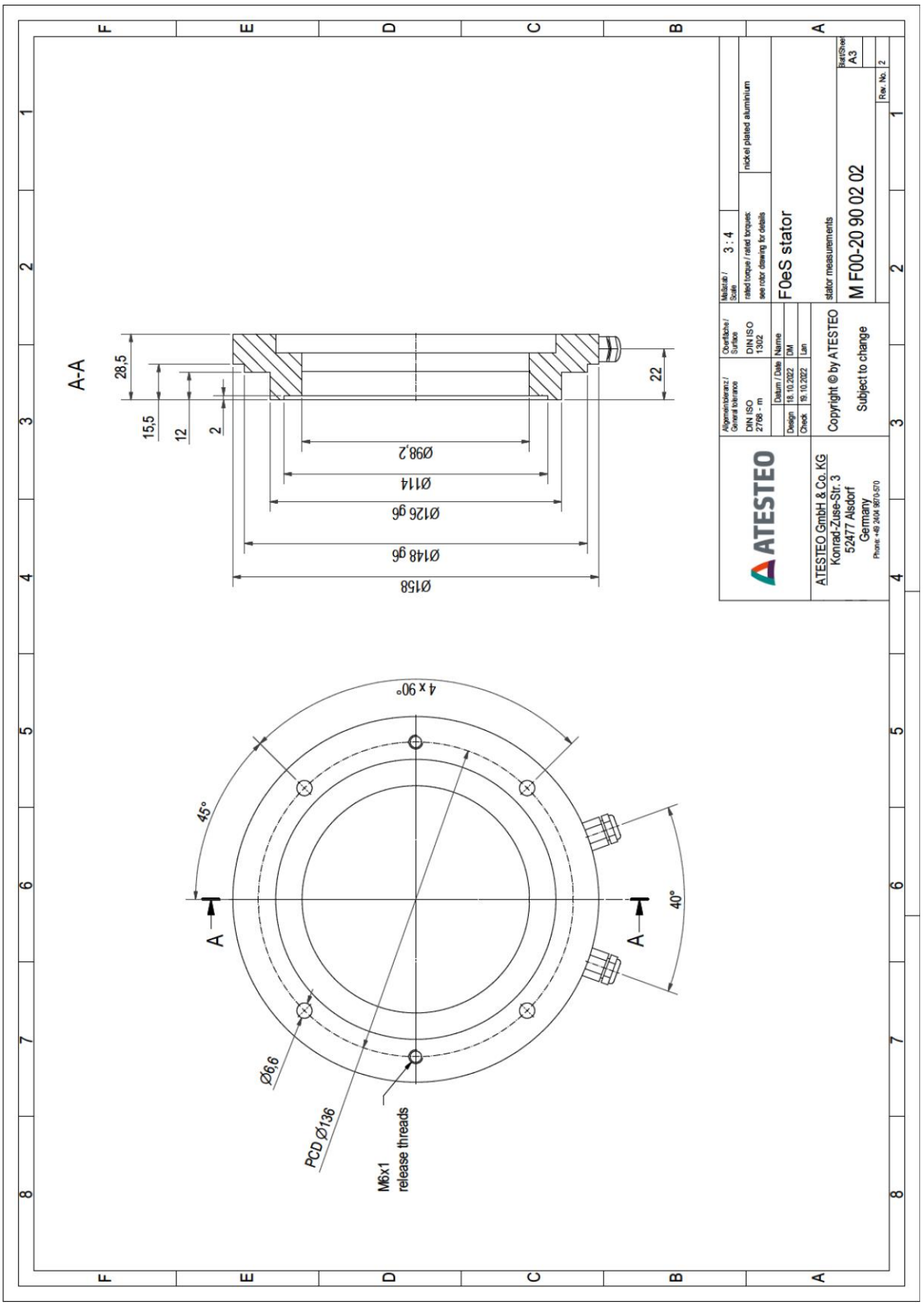


F0eS-SV (<=500 Nm)
Rotor

Drawing

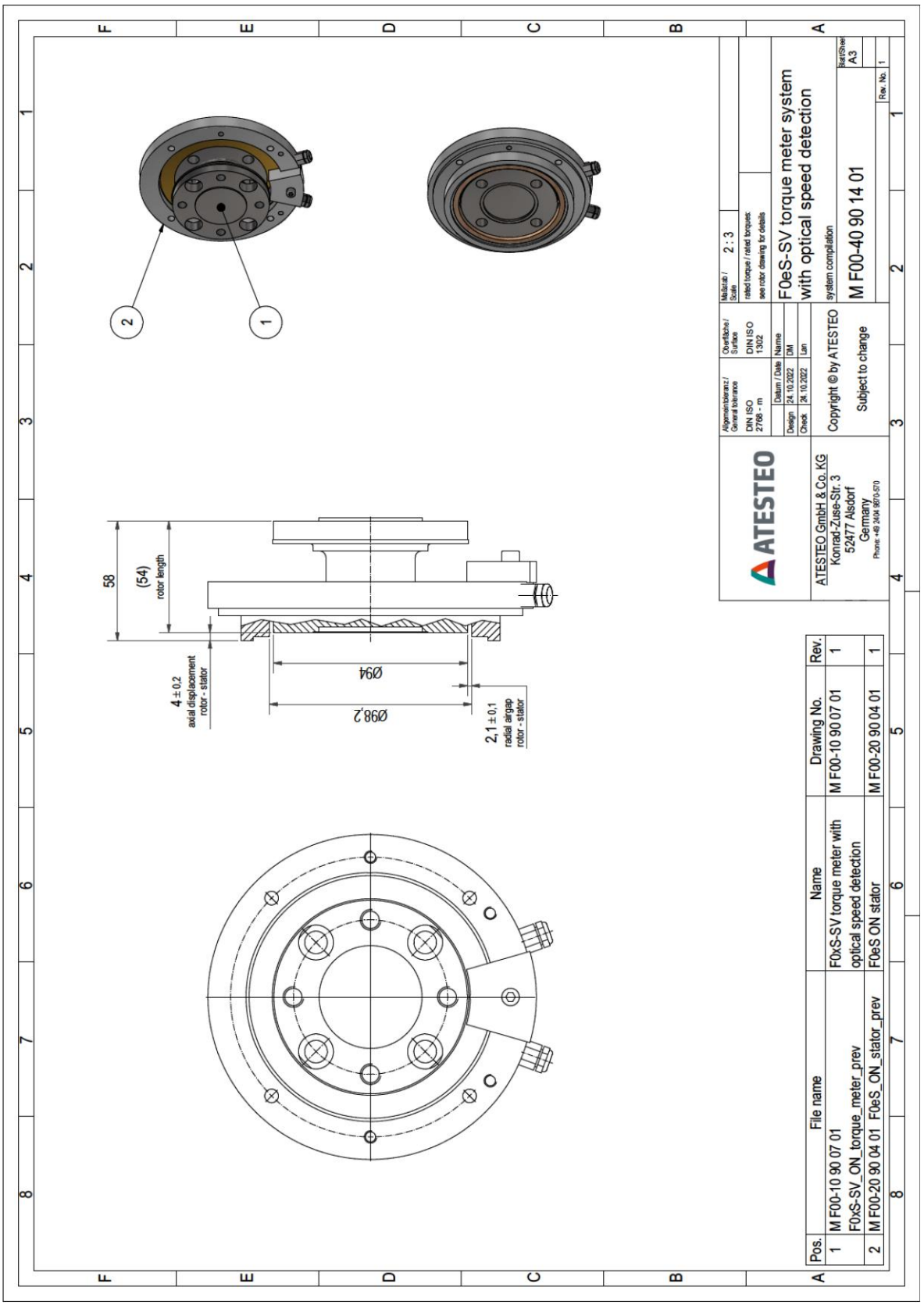


Drawing



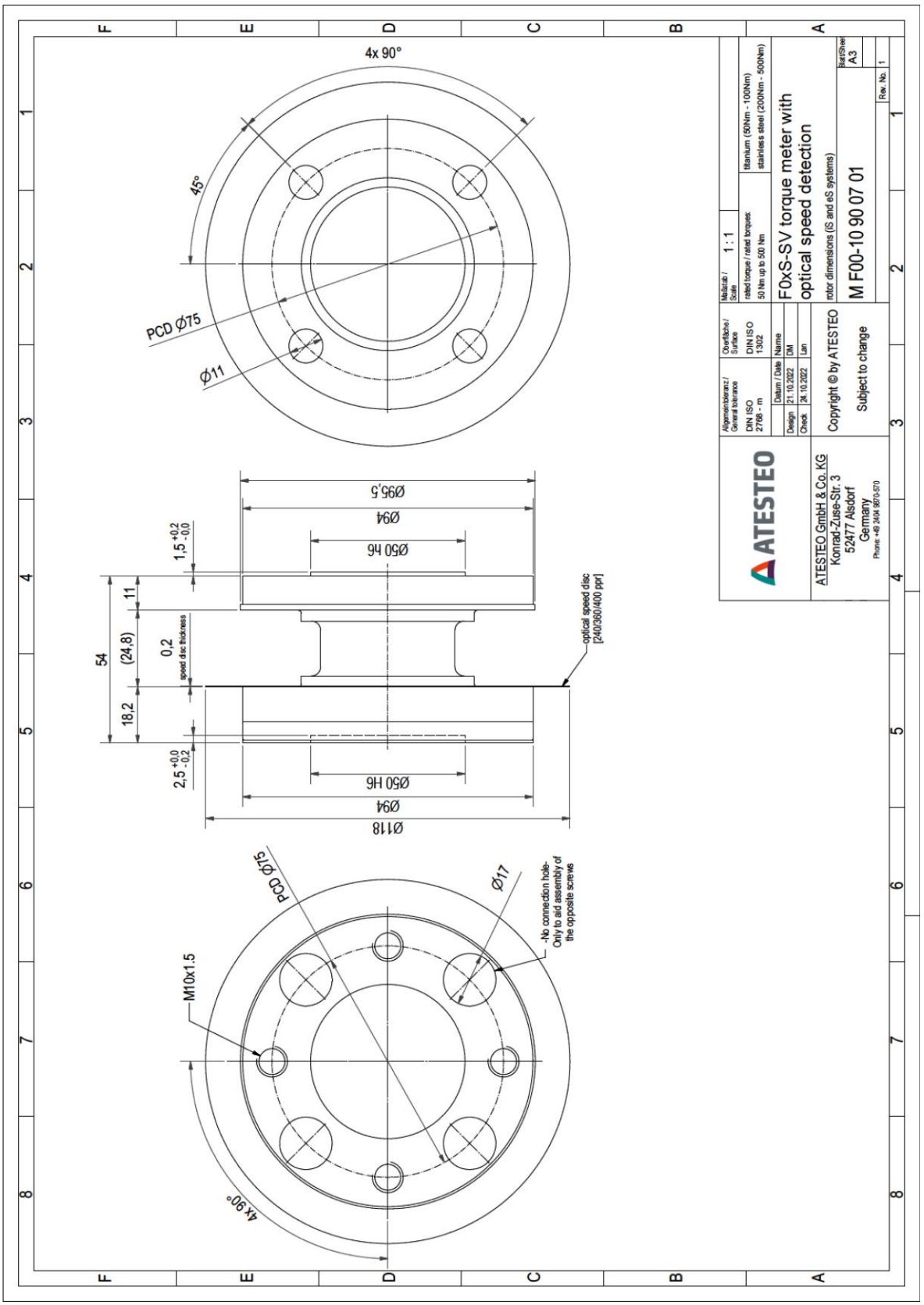
F0eS-SV SPD_OPT (<=500 Nm) System

Drawing

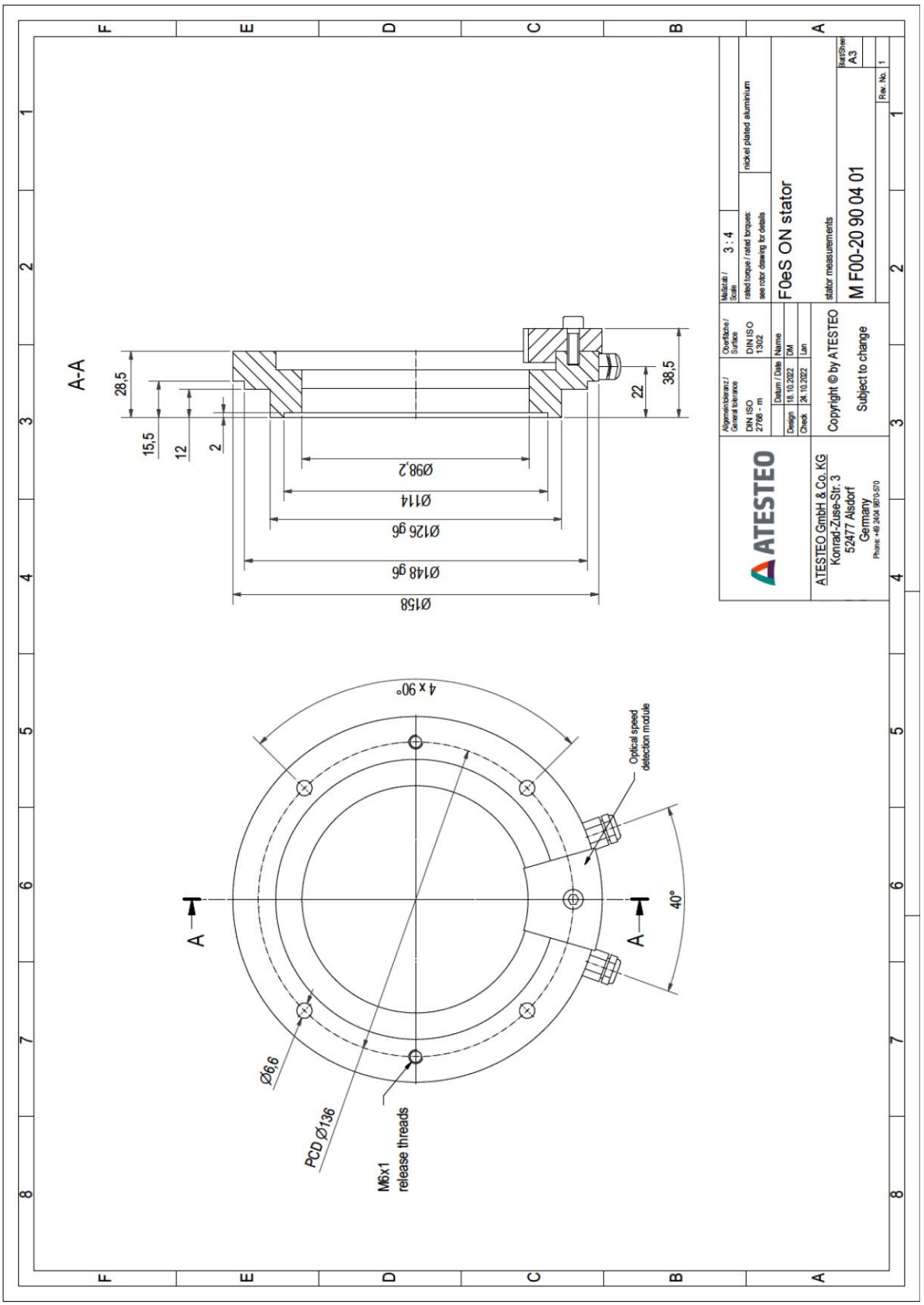


F0eS-SV SPD_OPT (<=500 Nm) Rotor

Drawing

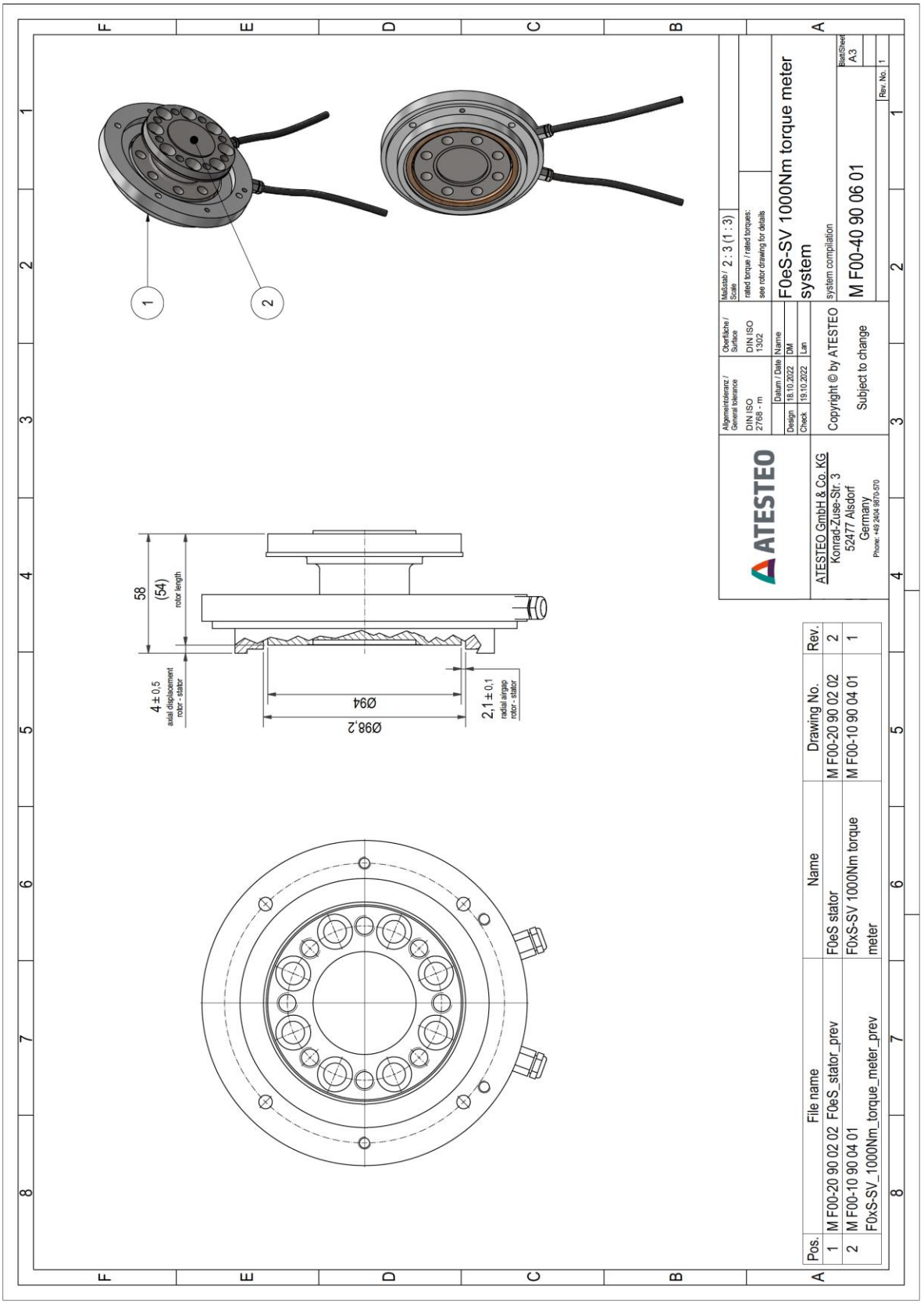


Drawing



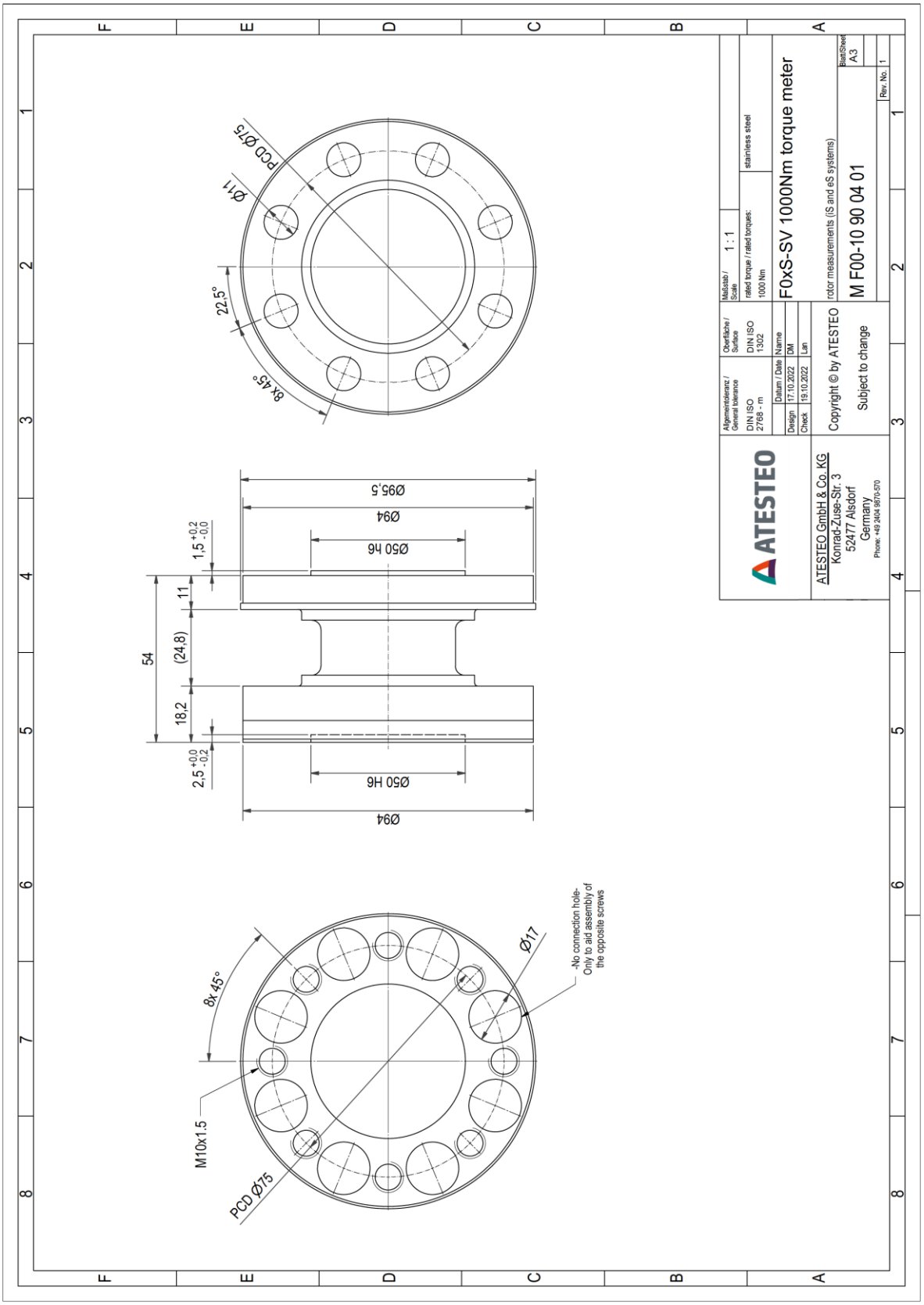
F0eS-SV (1000 Nm) System

Drawing



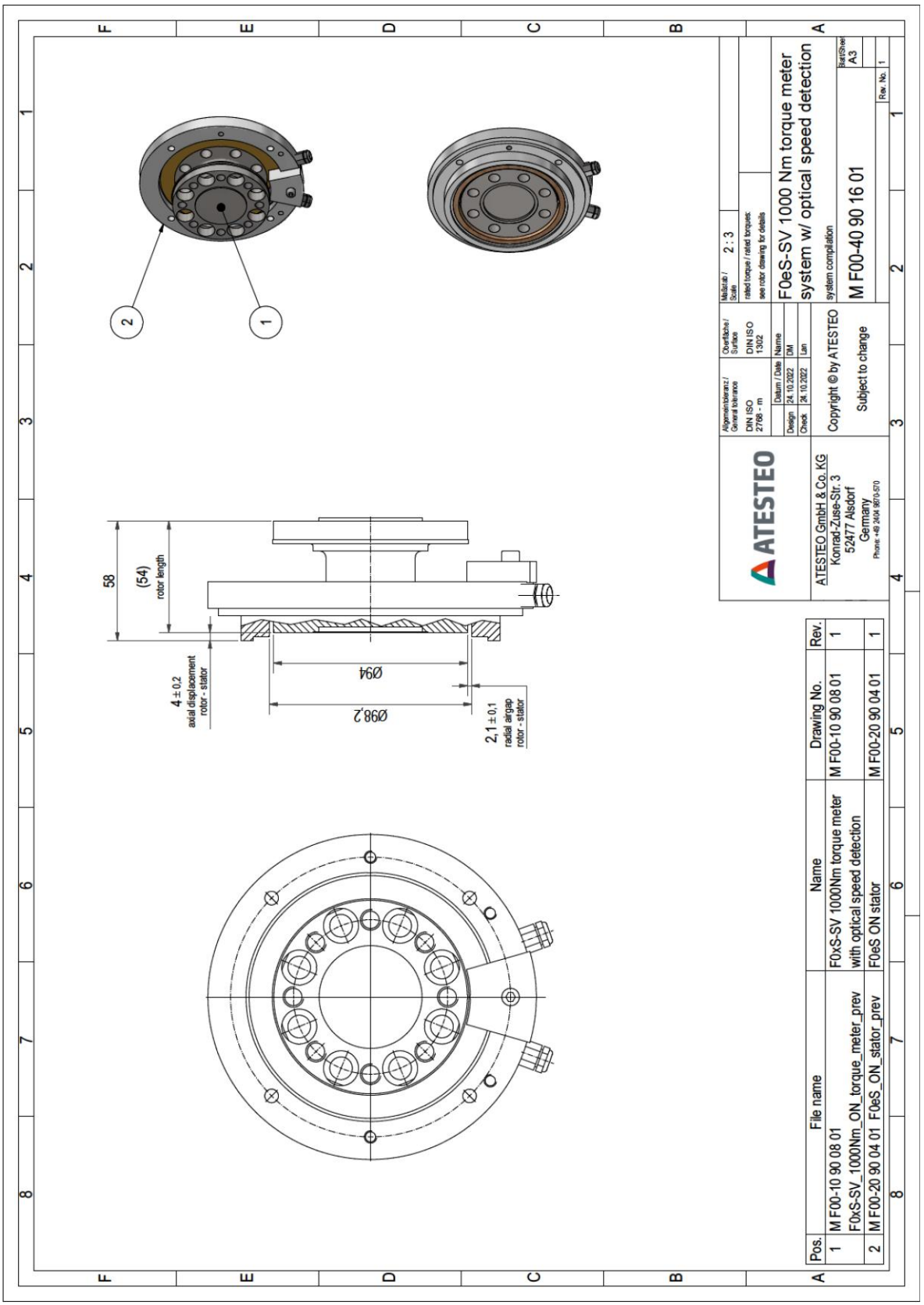
F0eS-SV (1000 Nm) System

Drawing



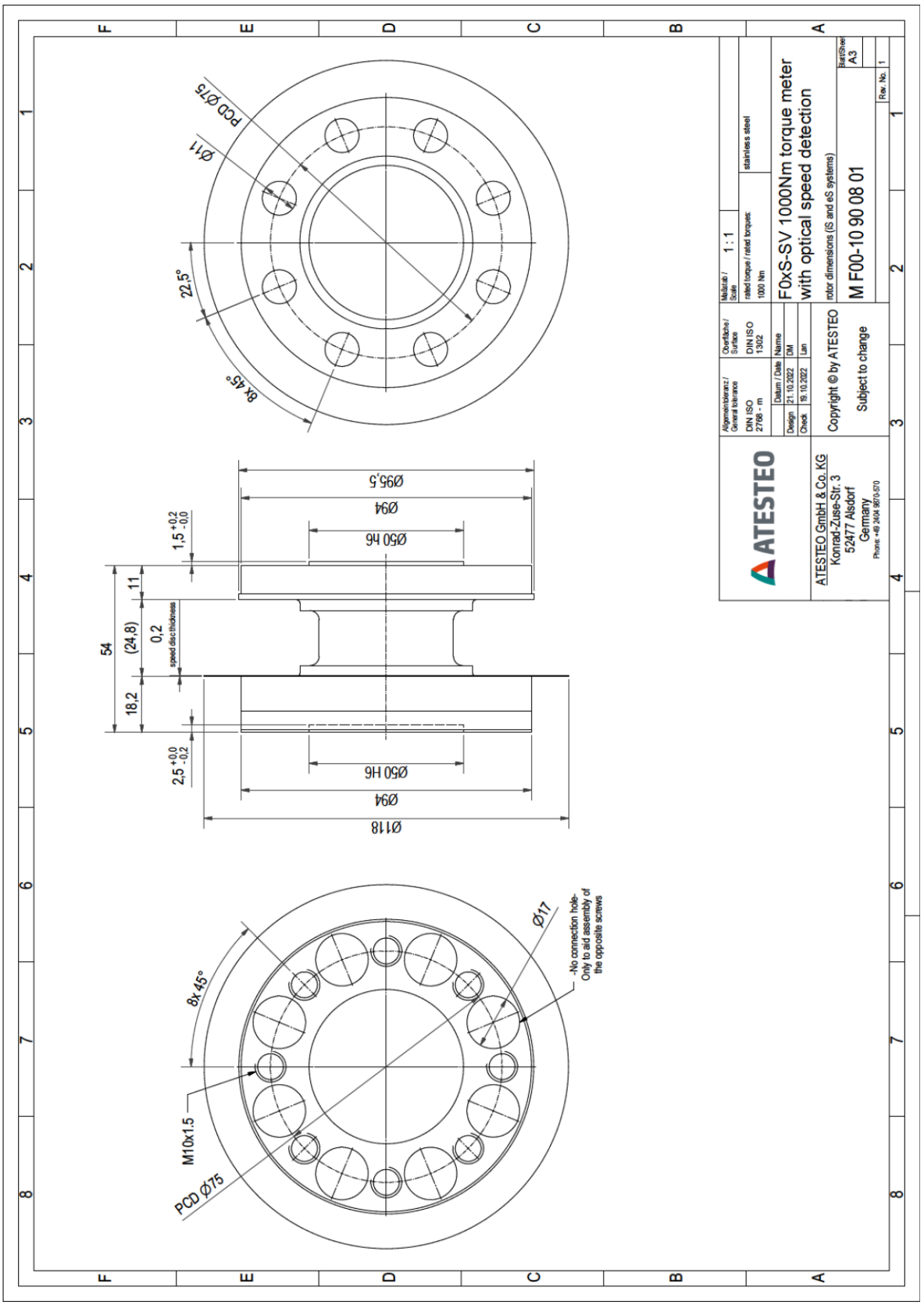
F0eS-SV SPD_OPT (1000 Nm) System

Drawing

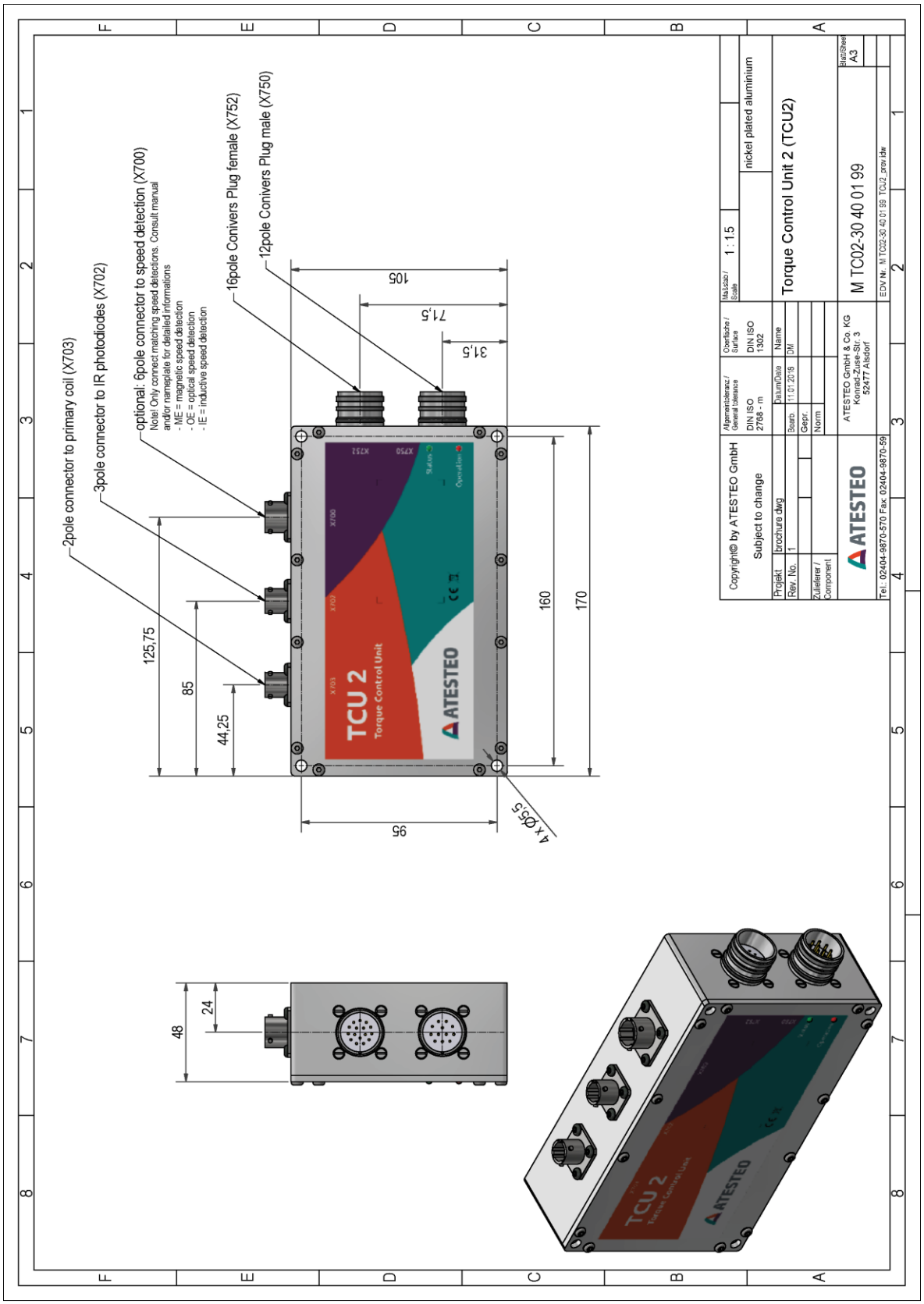


F0eS-SV SPD_OPT (1000 Nm) Rotor

Drawing



Drawing



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